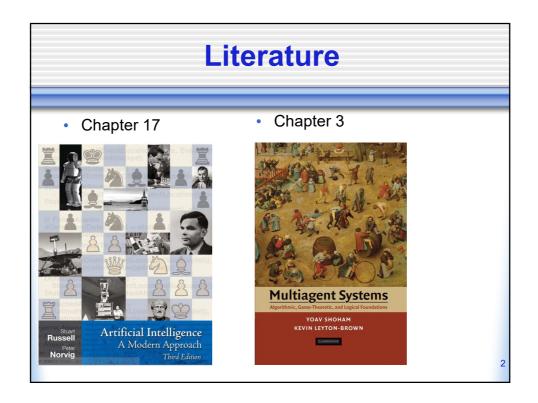
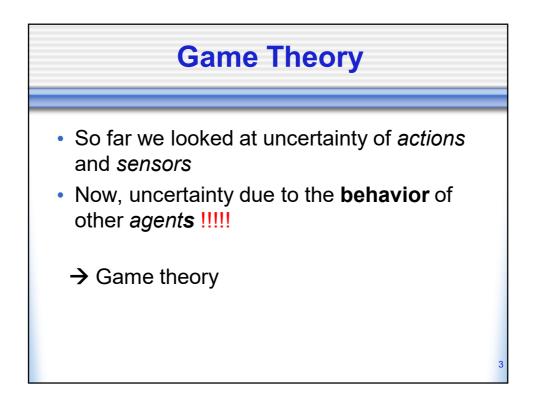
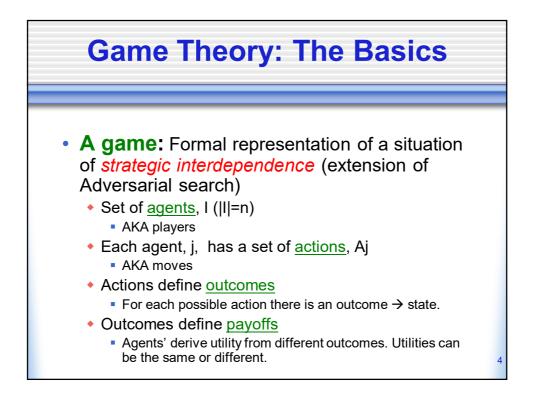
Intelligent Autonomous Agents and Cognitive Robotics

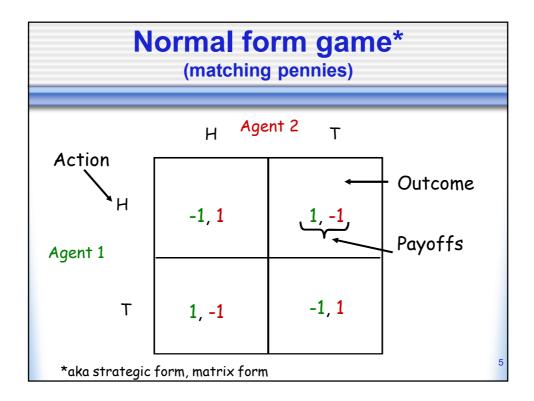
Topic 10: Agent**S** and Game Theory Topic 11: Social Choice (Preference Aggregation)

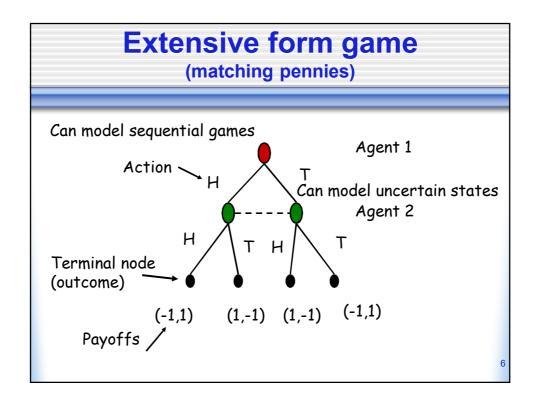
> Ralf Möller, Rainer Marrone Hamburg University of Technology

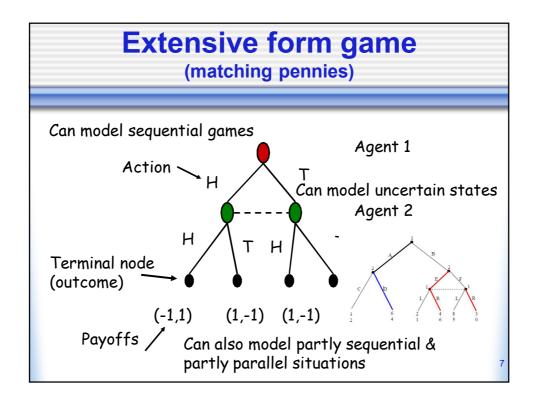


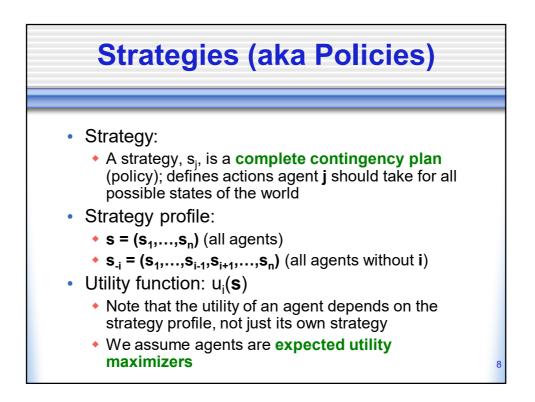


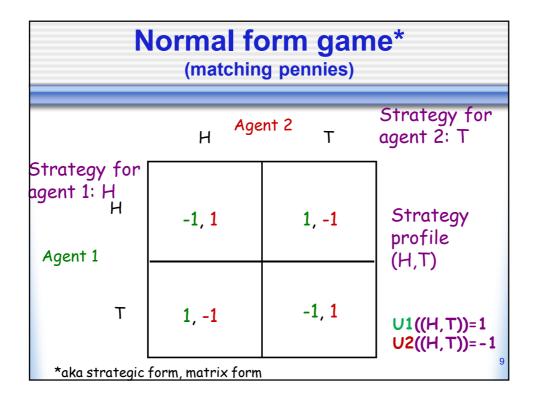


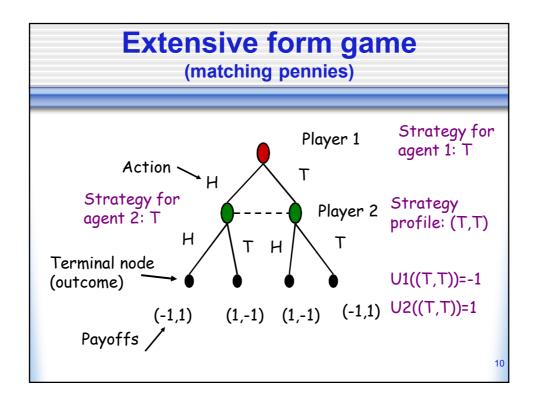


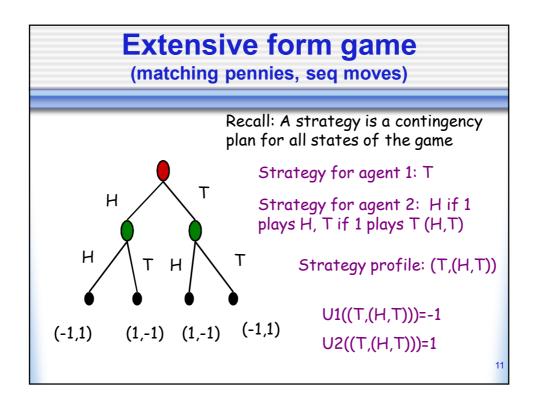


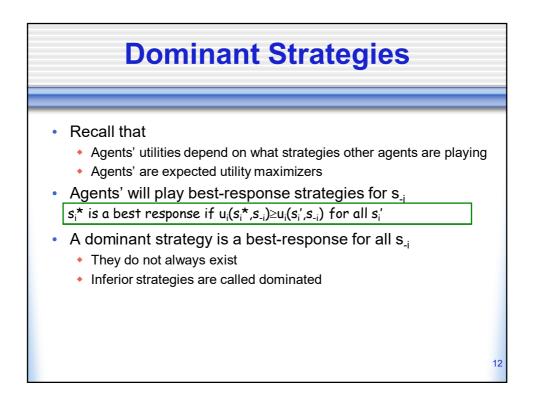


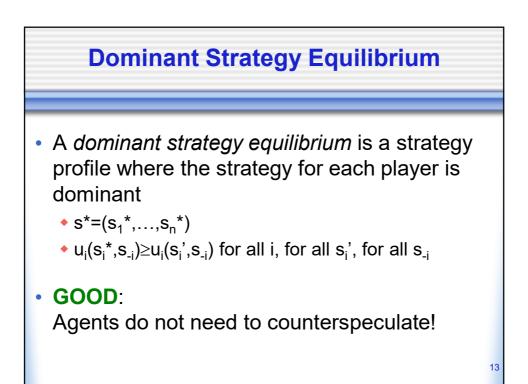


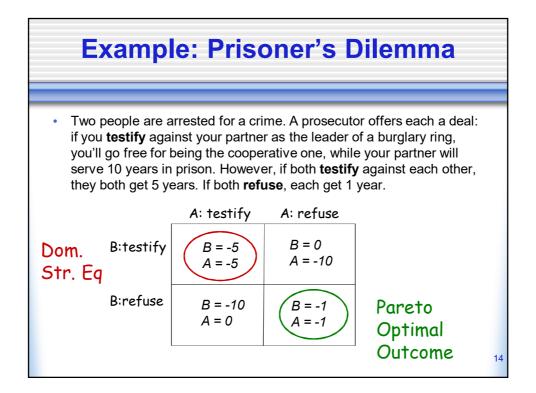


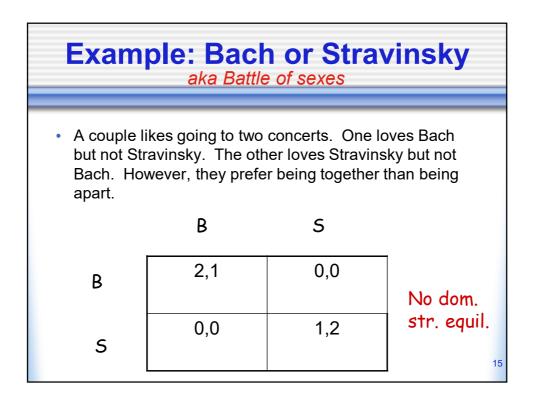


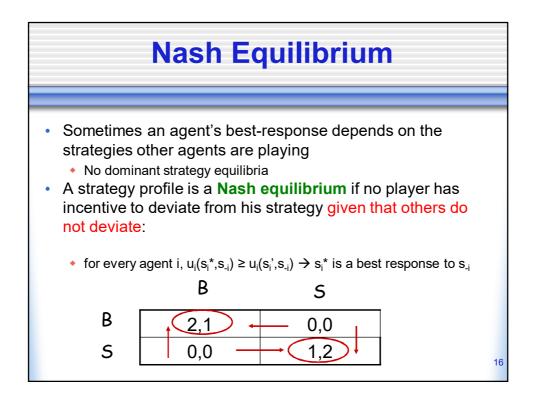


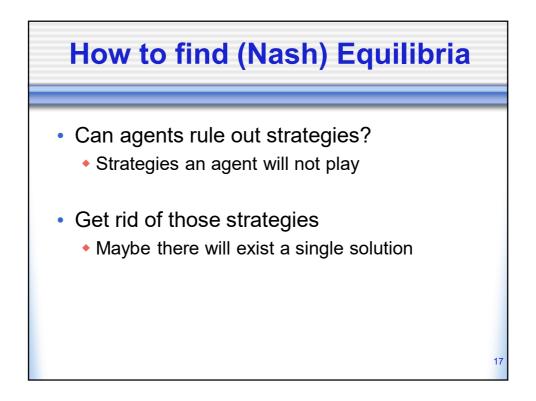


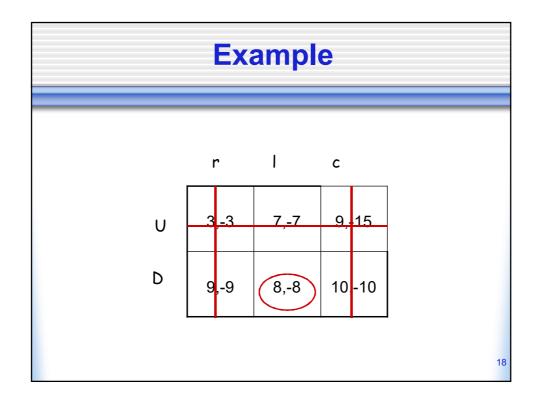














- Let Ri⊆Si be the set of removed strategies for agent i
- Initially Ri=Ø
- Choose agent i, and strategy s_i such that $s_i \in S_i \backslash R_i$ and there exists $s_i' \in S_i \backslash R_i$ such that

$$u_i(s'_i, s_{-i}) u_i(s_i, s_{-i})$$
 for all $s_{-i} \in S_{-i} \setminus R_{-i}$

- Add s_i to R_i, continue
- Thm: If a unique strategy profile, s*, survives then it is a Nash Eq.
- **Thm:** If a profile, s*, is a Nash Equilibrium then it must survive iterated elimination.



