Module 5: Integer Programs (IP versus LP)

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### Remark

We cannot **PROVE** an algorithm that is guaranteed to be fast does not exist, but we can show that it is "highly unlikely".

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We cannot **PROVE** that sometimes there is no short certificate of infeasibility, but we can show that it is "highly unlikely".

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Let us look at an example...

### Proposition

The following IP,

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 $x_1' = 2x_1 + 2x_2 \ge 1$  and  $x_2' = x_1 + 2x_2 \ge 1$  v

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$$x'_1 \qquad \stackrel{?}{\leq} \sqrt{2}x'_2$$

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$$\begin{array}{rcl}
x_1' & \stackrel{?}{\leq} \sqrt{2}x_2' \\
2x_1 + 2x_2 & \stackrel{?}{\leq} \sqrt{2} (x_1 + 2x_2)
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$$\begin{array}{rcl} x_1' & \stackrel{?}{\leq} \sqrt{2}x_2' & \Longleftrightarrow \\ 2x_1 + 2x_2 & \stackrel{?}{\leq} \sqrt{2}\left(x_1 + 2x_2\right) = \sqrt{2}x_1 + 2\sqrt{2}x_2 & \Longleftrightarrow \\ x_1(2 - \sqrt{2}) & \stackrel{?}{\leq} (2\sqrt{2} - 2)x_2 & \end{array}$$

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- > otherwise  $\sqrt{2}=\frac{x_1}{x_2}$  but  $\sqrt{2}$  is not a rational number

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Integer Programming can, in principle, be reduced to Linear Programming.

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#### Remark

This will NOT give us a practical procedure to solve IPs,

but it will suggest a strategy.

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 $C = \{a, b, c\}$ 

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The notion of a convex hull is well defined.

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- $C \subseteq H_1 \cap H_2$ ,
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- $H_1 \cap H_2$  is convex

However,  $H_1 \cap H_2$  is smaller than both  $H_1$  and  $H_2$ . This is a contradiction.

$$P = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} : \begin{pmatrix} -1 & 0 \\ 1 & -1 \\ -1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \le \begin{pmatrix} -3/2 \\ 5/2 \\ -3 \end{pmatrix} \begin{pmatrix} (1) \\ (2) \\ (3) \end{pmatrix} \right\}.$$

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Polyhedron

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The condition that all entries of A and b are rational numbers cannot be excluded from the hypothesis.

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# Example

Consider

$$P = \left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} : x_1 \le \sqrt{2}x_2, \ x_1, x_2 \ge 1 \right\}.$$

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<u>Goal</u>: Use Meyer's theorem to reduce the problem of solving Integer Programs, to the problem of solving Linear Program.

# $\max\{c^{\top}x : Ax \le b, x \text{ integer}\}.$ (IP)

$$\max\{c^{\top}x : Ax \le b, x \text{ integer}\}.$$
 (IP)

The convex hull of the feasible sol. of (IP) is a polyhedron  $\{x : A'x \leq b'\}$ .

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## Theorem

• (IP) is infeasible if and only if (LP) is infeasible,

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Conceptual way of solving (IP):

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$$\max\left\{ \begin{pmatrix} 1 & 1 \end{pmatrix} x : \begin{pmatrix} 2 & 1 \\ 1 & 2 \\ -1 & -4 \\ -1 & 0 \end{pmatrix} x \le \begin{pmatrix} 7 \\ 7 \\ -4 \\ -\frac{1}{2} \end{pmatrix} \quad \begin{array}{c} (1) \\ (2) \\ (3) \\ (4) \end{array} x \text{ integer} \right\}$$
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$$\overset{x_{2}}{\overset{(4)}{\overset{(4)}{\overset{(4)}{\overset{(1)}{\overset{(1)}{\overset{(2)$$



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This is NOT a practical way to solve an Integer Program.

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#### Remark

This is NOT a practical way to solve an Integer Program.

Why Not?

- We do not know how to compute  $A^\prime, b^\prime,$  and
- A', b' can be MUCH more complicated than A, b.

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Construct an approximation of the convex hull of the solutions of (IP).

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# Recap

• Integer Programs are much harder to solve than Linear Programs.

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Construct an approximation of the convex hull of the solutions of (IP).

- Integer Programs are much harder to solve than Linear Programs.
- Linear Programming theory does not extend to Integer Programs.

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Construct an approximation of the convex hull of the solutions of (IP).

- Integer Programs are much harder to solve than Linear Programs.
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- The convex hull of the integer points in a rational polyhedron is a polyhedron.

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Construct an approximation of the convex hull of the solutions of (IP).

- Integer Programs are much harder to solve than Linear Programs.
- Linear Programming theory does not extend to Integer Programs.
- We defined the notion of convex hulls.
- The convex hull of the integer points in a rational polyhedron is a polyhedron.
- Integer programming reduces to Linear programming, but it is NOT a practical reduction.