

Module 6: Nonlinear Programs (Convexity)

Definition

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where

$$f : \mathbb{R}^n \rightarrow \mathbb{R}, \text{ and}$$

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There aren't any restrictions regarding the type of functions.

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This is a very general model, but NLPs can be very hard to solve!

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$$\begin{array}{ll} \min & x_2 \\ \text{s.t.} & \\ & -x_1^2 - x_2 + 2 \leq 0 \\ & x_2 - \frac{3}{2} \leq 0 \\ & x_1 - \frac{3}{2} \leq 0 \\ & -x_1 - 2 \leq 0 \end{array}$$

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min x_2

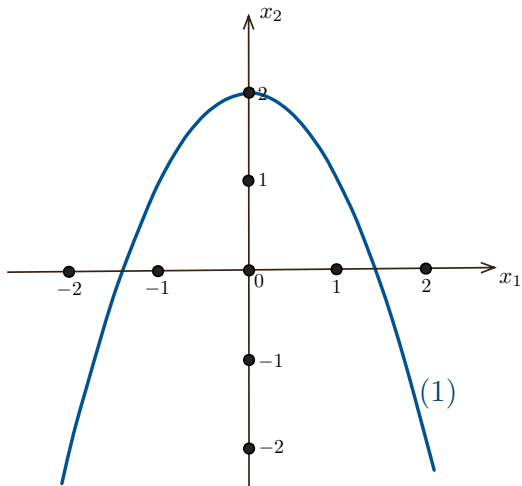
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(1) $x_2 \geq 2 - x_1^2$.

min x_2

s.t.

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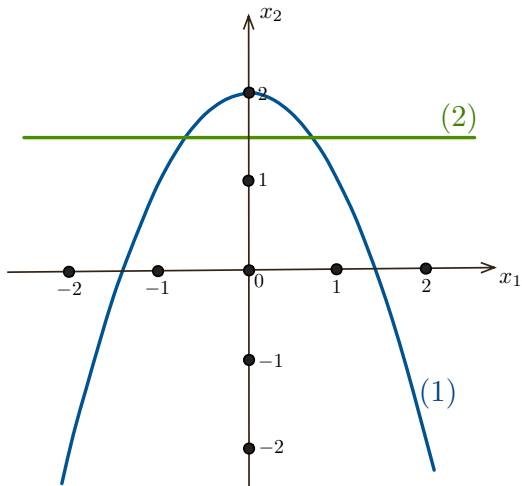
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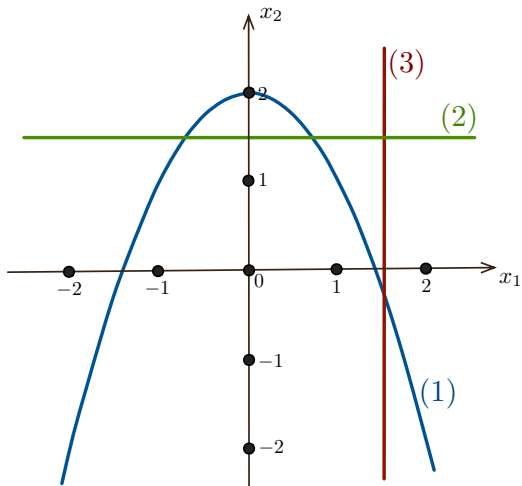
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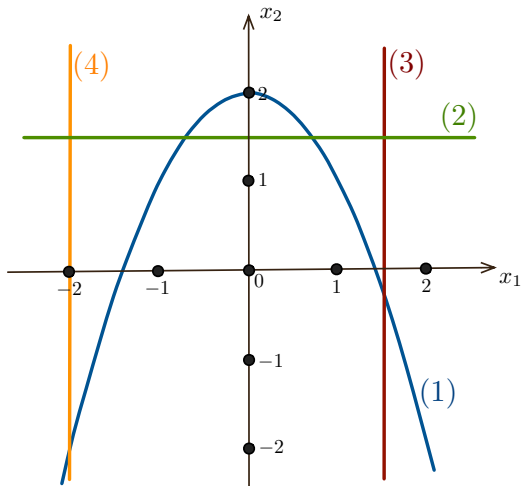
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$$(4) x_1 \geq -2.$$

min x_2

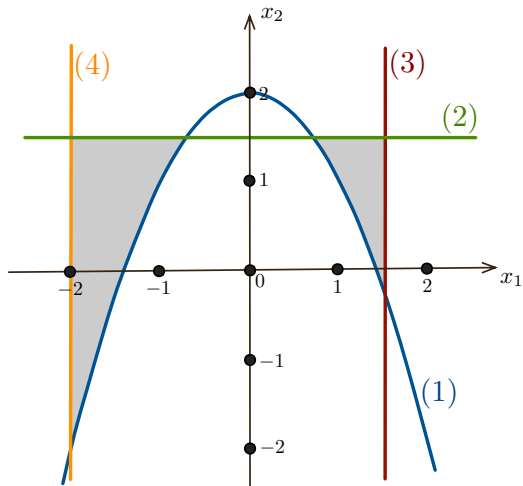
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FEASIBLE REGION

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Remark

We may assume $f(x)$ is a **linear function**, i.e., $f(x) = c^\top x$.

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We can rewrite (P) as

$$\begin{array}{ll} \min & \lambda \\ \text{s.t.} & \\ & \lambda \geq f(x) \\ & g_i(x) \leq 0 \quad (i = 1, \dots, k) \end{array} \quad (\text{Q})$$

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The optimal solution to (Q) will have $\lambda = f(x)$.

Nonlinear Programs Generalize Linear Programs

$$\max \quad x_1 + x_2$$

s.t.

$$2x_1 - x_2 \geq 3$$

$$x_1 - x_2 = 4$$

$$x_1, x_2 \geq 0$$

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Nonlinear Programs can also generalize **INTEGER PROGRAMS!**

Nonlinear Programs Generalize **Integer** Programs

$$\max \quad c^\top x$$

s.t.

$$Ax \leq b$$

$$x_j \in \{0, 1\} \quad (j = 1, \dots, n)$$

0, 1 IP

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$$x_j \in \{0, 1\} \quad \iff \quad x_j(1 - x_j) = 0$$

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$$x_j \in \{0, 1\} \quad \iff \quad x_j(1 - x_j) = 0$$

$$\min \quad -c^\top x$$

s.t.

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$$x_j(1 - x_j) \leq 0 \quad (j = 1, \dots, n)$$

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Quadratic NLP

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Quadratic NLP

Remark

0, 1 IPs are hard to solve; thus, quadratic NLPs are also hard to solve.

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$$x_j \text{ integer} \iff \sin(\pi x_j) = 0.$$

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IPs are hard to solve; thus, NLPs are also hard to solve.

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What makes solving an NLP hard?

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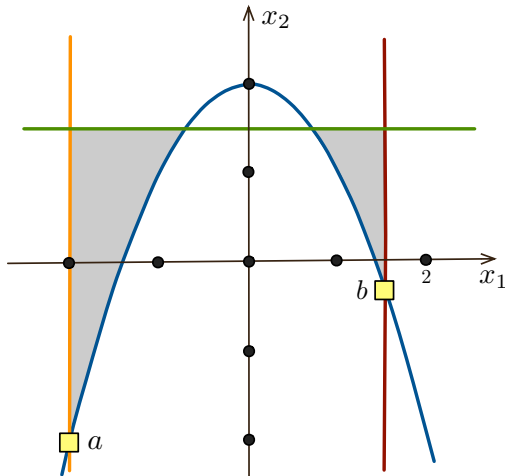
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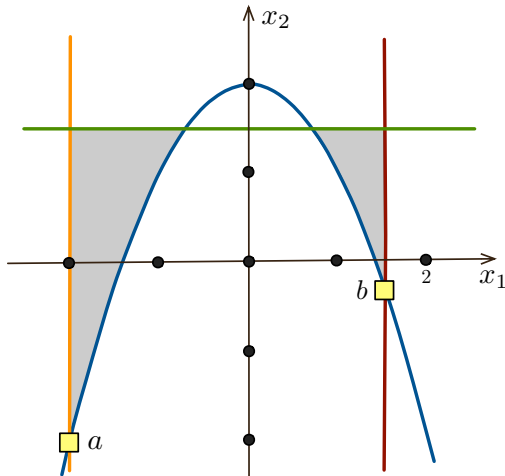


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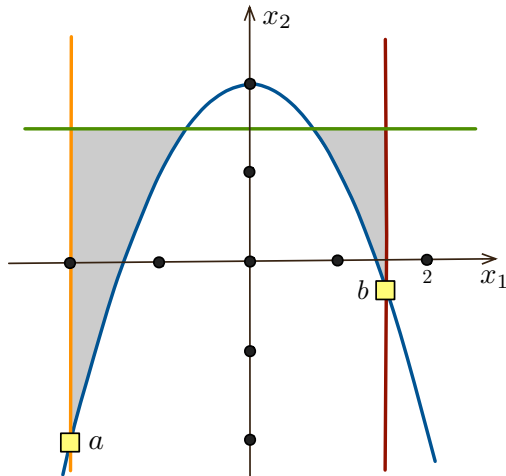
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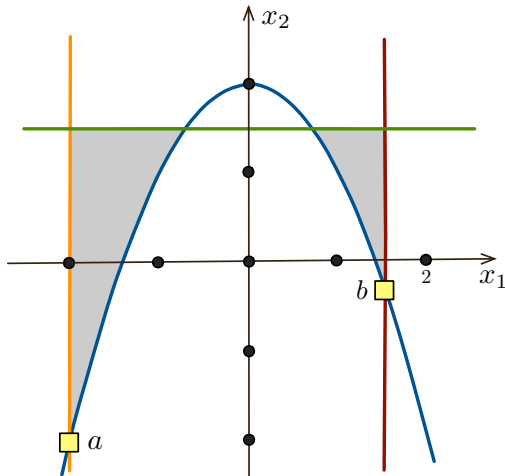
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b is a local optimum



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$$\min \{f(x) : x \in S\}. \quad (\text{P})$$

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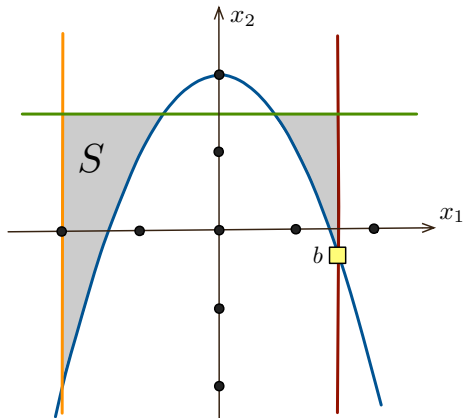
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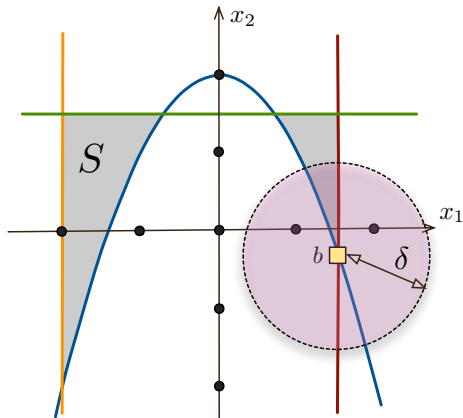
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Proposition

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If S is **convex** and x is a **local optimum**, then x is optimal.

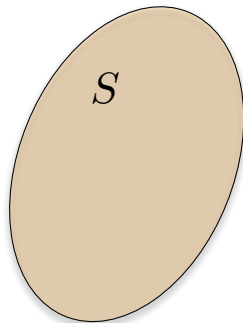
Proposition

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$$\min \{c^T x : x \in S\}. \quad (\text{P})$$

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Proof



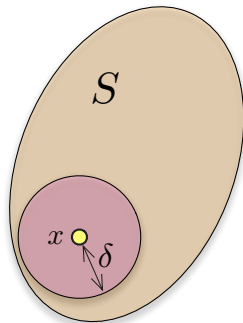
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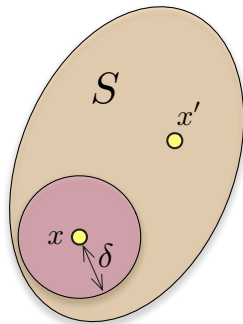
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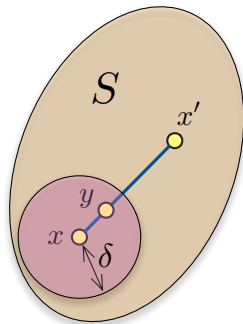
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Let $y = \lambda x' + (1 - \lambda)x$ for $\lambda > 0$ small.



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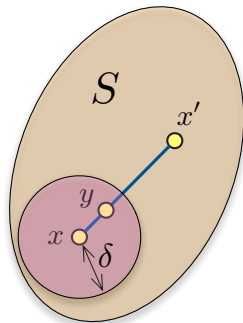
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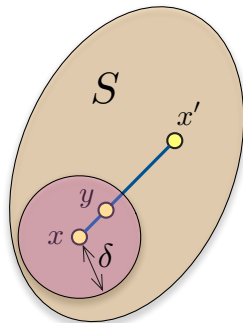
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Since S is convex, $y \in S$.



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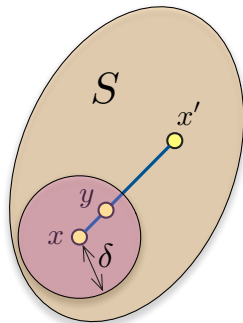
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If S is **convex** and x is a **local optimum**, then x is optimal.

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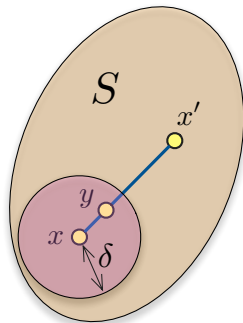
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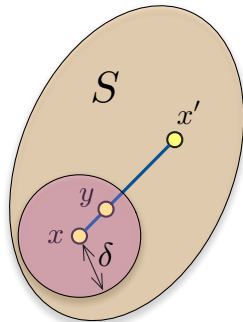
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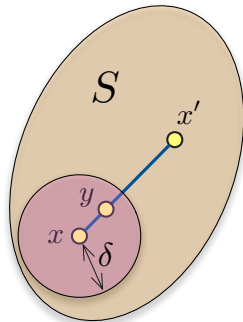
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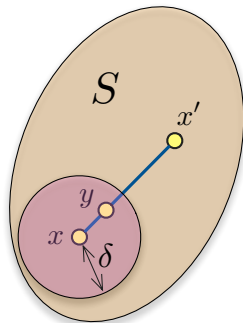
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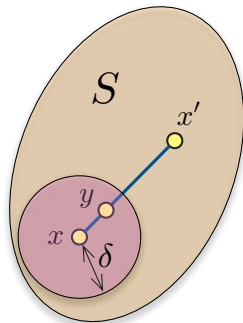
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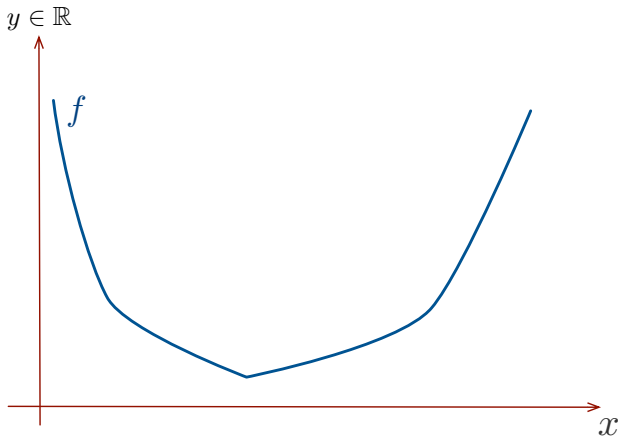
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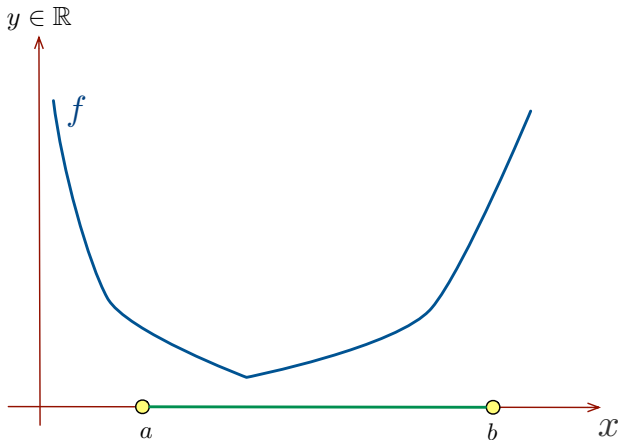


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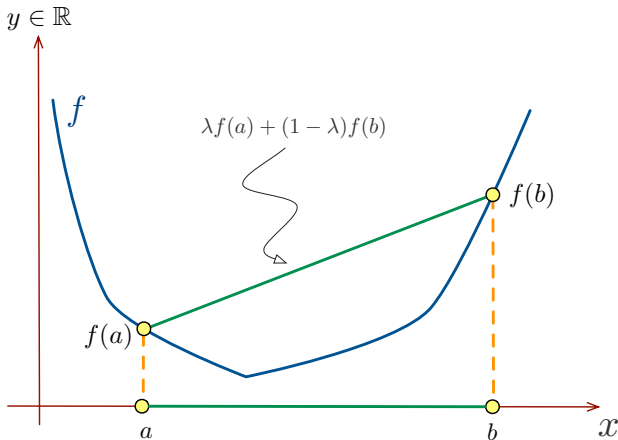


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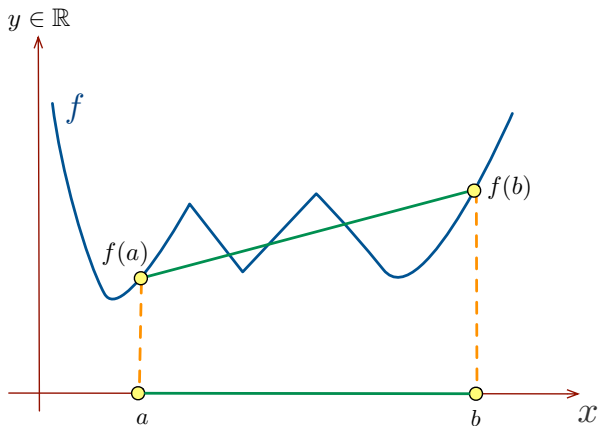
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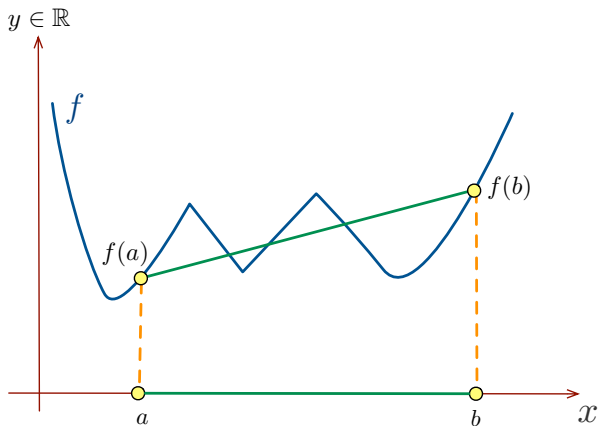
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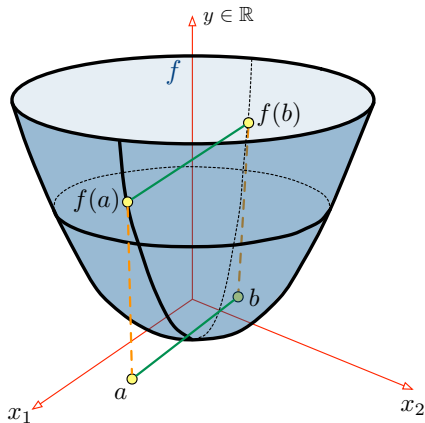
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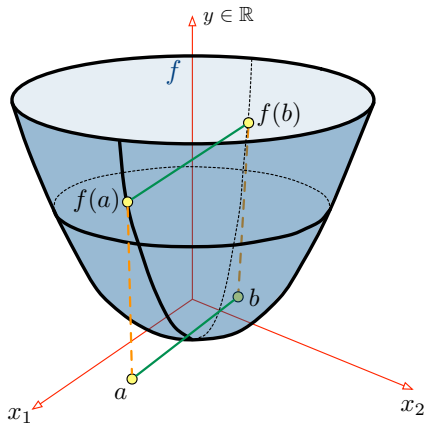
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Why Do We Care About Convex Functions?

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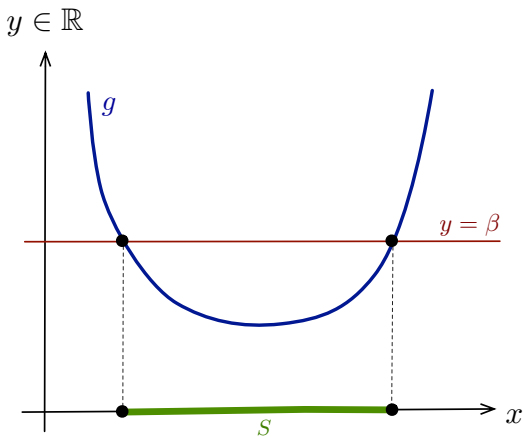
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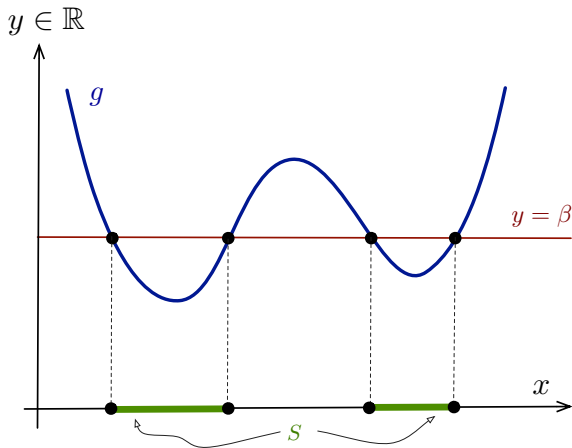
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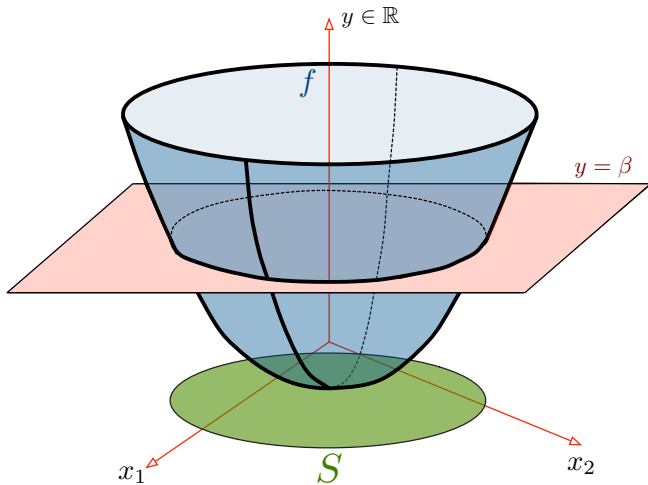
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Since the intersection of convex sets is convex, the result follows.

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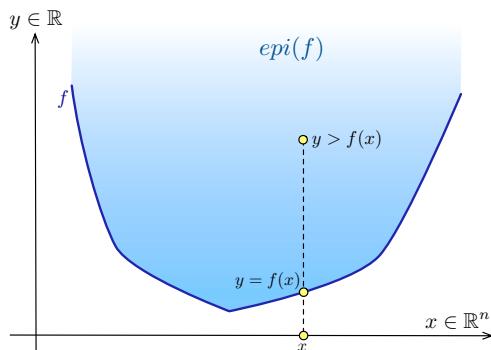
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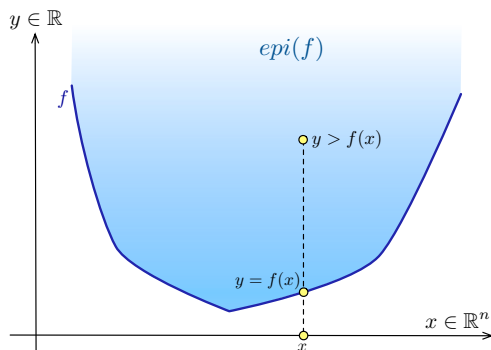


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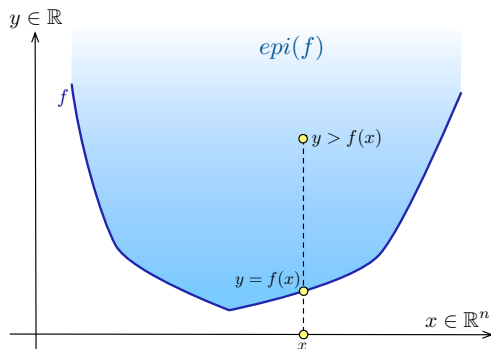
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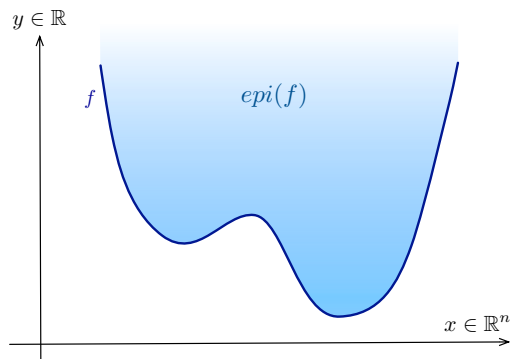
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Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a function. The **epigraph** of f is then given by,

$$\text{epi}(f) = \left\{ \begin{pmatrix} y \\ x \end{pmatrix} : x \in \mathbb{R}^n, y \in \mathbb{R}, y \geq f(x) \right\} \subseteq \mathbb{R}^{n+1}.$$

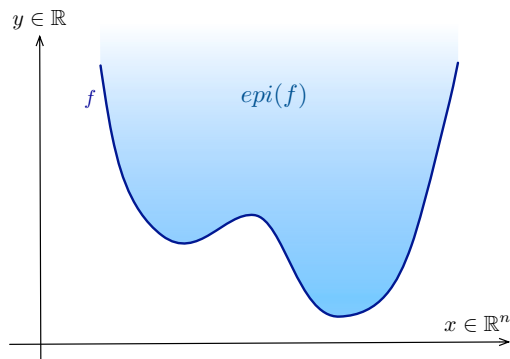


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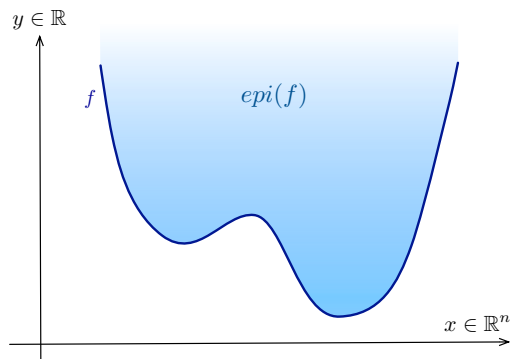
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Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a function. Then

1. f is convex \implies $\text{epi}(f)$ is convex.
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To show: $\text{epi}(f)$ contains

$$\lambda \begin{pmatrix} \alpha \\ a \end{pmatrix} + (1 - \lambda) \begin{pmatrix} \beta \\ b \end{pmatrix}$$

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$$\begin{aligned} f(\lambda a + (1 - \lambda)b) &\leq && \text{(convexity of } f) \\ \lambda f(a) + (1 - \lambda)f(b) &&& \end{aligned}$$

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$$f(\lambda a + (1 - \lambda)b) \leq \underbrace{\lambda}_{\geq 0} \underbrace{f(a)}_{\leq \alpha} + \underbrace{(1 - \lambda)}_{\geq 0} \underbrace{f(b)}_{\leq \beta} \quad (\text{convexity of } f)$$

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Thus $(*)$ is in $\text{epi}(f)$.

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3. Local optimum = optimal sol when the feasible region is convex.
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5. Convex functions yield a convex feasible region.
6. Convex functions and convex sets are related by epigraphs.