Medical Imaging

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Non-Equidistant Fast Fourier Transform

Non-Equidistant Fast Fourier Transform

The non-equidistant fast Fourier transform (NFFT) is an approximative algorithm that performs the non-equidistant discrete Fourier transform (NDFT) efficiently.

Definition

The NDFT is defined as

$$f_j = f(x_j) = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_k e^{-2\pi i k x_j}, \quad j = 0, \dots, M-1$$

It takes a sequence of N equidistantly distributed samples \hat{f}_k and calculates the Fourier sum at M non-equidistant sampling nodes $x_i \in [-0.5, 0.5)$.

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Non-Equidistant Fast Fourier Transform

Remarks

- Naive NDFT would require $\mathcal{O}(MN)$ arithmetic operations
- The FFT requires x_j to be equidistant, i.e.

$$x_j = -\frac{1}{2} + \frac{j}{N}, \qquad j = 0, \dots, N-1$$

Key Idea of the NFFT

The key idea of the NFFT is to approximate the *anharmonic* complex exponential $e^{-2\pi i k x_j}$ by a sum of harmonic complex exponentials

$$\underbrace{\mathrm{e}^{-2\pi\mathrm{i}\,kx_{j}}}_{\text{anharmonic}} \approx \sum_{I=-\frac{L}{2}}^{\frac{L}{2}-1} \beta_{I,j} \underbrace{\mathrm{e}^{-2\pi\mathrm{i}\,\frac{kI}{L}}}_{\text{harmonic}}$$

Remarks

- Harmonic here is means that the frequency $\gamma_l = \frac{l}{L}$ is a multiple of the basis frequency $\gamma_1 = \frac{1}{L}$.
- Similar to other approximations (or interpolations) we use a base function and shift its frequency (c.f. spline interpolation).
- Most important point of the approximation is that the two indices k and j are not in the exponent anymore but they are factorized.

We consider a general window function

$$\varphi \in L^1(\mathbb{R}) \cap L^2(\mathbb{R}) \cap \mathsf{BV}(\mathbb{R})$$
 and its periodization

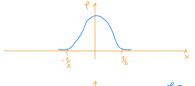
$$\tilde{\varphi}(\tilde{x}) := \sum_{p=-\infty}^{\infty} \varphi(\tilde{x}+p).$$

The function has a uniformly convergent Fourier series

$$ilde{arphi}(ilde{x}) = \sum_{k=-\infty}^{\infty} c_k(ilde{arphi}) \mathrm{e}^{-2\pi \mathrm{i} k ilde{x}}$$

with coefficients

$$c_k(ilde{arphi}) = \int_{-rac{1}{2}}^{rac{1}{2}} ilde{arphi}(ilde{x}) \mathrm{e}^{2\pi \mathrm{i} k ilde{x}} \, \mathsf{d} ilde{x}$$





Note: The sign is flipped compared to the regular definition of the Fourier series.

We now substitute \tilde{x} by $\tilde{x}=x-x'$ with $x\in\mathbb{R}$ yielding with $\frac{\mathrm{d}\tilde{x}}{\mathrm{d}x'}=-1$

$$c_k(\tilde{\varphi}) = \int_{x+\frac{1}{2}}^{x-\frac{1}{2}} \tilde{\varphi}(x-x') e^{2\pi i k(x-x')} (-1) dx'$$

$$\stackrel{\text{periodicity}}{=} \int_{\frac{1}{2}}^{-\frac{1}{2}} \tilde{\varphi}(x-x') e^{2\pi i k(x-x')} (-1) dx'$$

$$= \int_{-\frac{1}{2}}^{\frac{1}{2}} \tilde{\varphi}(x-x') e^{2\pi i k(x-x')} dx'$$

Then we approximate the integral at equidistant nodes $\frac{1}{L}$ using a rectangular quadrature rule

$$c_k(\tilde{\varphi}) pprox rac{1}{L} \sum_{l=-rac{L}{2}}^{rac{L}{2}-1} \tilde{\varphi}\left(x-rac{l}{L}
ight) \mathrm{e}^{2\pi \mathrm{i} k(x-rac{l}{L})}$$

We will later chose $L = \alpha N$ where $\alpha > 1$ is the so-called *oversampling factor*. If $c_k(\tilde{\varphi}) \neq 0$ we obtain

$$e^{-2\pi i k x} \approx \frac{1}{\alpha N c_k(\tilde{\varphi})} \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1} \tilde{\varphi}\left(x - \frac{l}{\alpha N}\right) e^{-2\pi i k \frac{l}{\alpha N}}$$
(1)

Thus we can indeed approximate the anharmonic exponential by a sum of harmonic exponentials $(\beta_{l,j} = \frac{1}{\alpha N c_l(\tilde{\varphi})} \tilde{\varphi} \left(x - \frac{l}{\alpha N} \right))$.

Since φ is a kernel function we know that only few of the summands in (1) have a significant contribution to the sum.

Key idea: Consider only significant summands such that the sum needs just be evaluated partially.

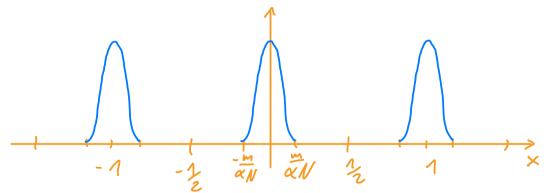
To this end we truncate the function φ at $\pm \frac{m}{\alpha N}$ and replace it by

$$\psi(x) := \begin{cases} \varphi(x) & \text{if } x \in \left[-\frac{m}{\alpha N}, \frac{m}{\alpha N} \right] \\ 0 & \text{else} \end{cases}.$$

With the periodization $\tilde{\psi}(\tilde{x}) := \sum_{p=-\infty}^{\infty} \psi(\tilde{x}+p)$ this yields our final approximation

$$e^{-2\pi i k x} \approx \frac{1}{\alpha N c_k(\tilde{\varphi})} \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1} \tilde{\psi}\left(x - \frac{l}{\alpha N}\right) e^{-2\pi i k \frac{l}{\alpha N}}$$
(2)

Illustration of the truncation:



We now get back to the NDFT and replace the term ${\rm e}^{-2\pi {\rm i}kx}$ with our approximation yielding

$$f_{j} = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_{k} e^{-2\pi i k x_{j}}$$

$$\stackrel{(2)}{\approx} \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_{k} \frac{1}{\alpha N c_{k}(\tilde{\varphi})} \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1} \tilde{\psi} \left(x_{j} - \frac{l}{\alpha N}\right) e^{-2\pi i k \frac{l}{\alpha N}}$$

$$= \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1} \tilde{\psi} \left(x_{j} - \frac{l}{\alpha N}\right) \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \underbrace{\frac{\hat{f}_{k}}{\alpha N c_{k}(\tilde{\varphi})}}_{\text{apodization}} e^{-2\pi i k \frac{l}{\alpha N}}$$

$$\xrightarrow{\text{DFT/FFT}}_{\text{discrete convolution}}$$

Algorithm NFFT

Algorithm 1 Pseudocode NFFT

input:
$$\hat{f}_k \in \mathbb{C}$$
, $k = -\frac{N}{2}, \dots, \frac{N}{2} - 1$, $x_j \in [-\frac{1}{2}, \frac{1}{2})$, $j = 0, \dots, M - 1$, $\alpha > 1$ and $m \in \mathbb{N}$ output: $f_j \in \mathbb{C}$, $j = 0, \dots, M - 1$

1: **for**
$$k = -\frac{N}{2}, \dots, \frac{N}{2} - 1$$
 do

2:
$$\hat{g}_k = \frac{\hat{f}_k}{\alpha N c_k(\tilde{\varphi})}$$

3: end for

4: compute the data $(g_l)_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1}$ using an FFT of $(\hat{g}_k)_{k=-\frac{N}{2}}^{\frac{N}{2}-1}$.

5: **for**
$$j = 0, ..., M - 1$$
 do

6:
$$f_{j} = \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2}-1} g_{l} \tilde{\psi} \left(x_{j} - \frac{l}{\alpha N} \right)$$

7: end for

Complexity Analysis

The three steps have an individual time complexity of

- 1. $\mathcal{O}(N)$
- 2. $\mathcal{O}(\alpha N \log(\alpha N))$
- 3. $\mathcal{O}(mM)$

Thus, the total complexity of the NFFT is

$$\mathcal{O}(\alpha N \log(\alpha N) + mM) \ll \mathcal{O}(NM)$$

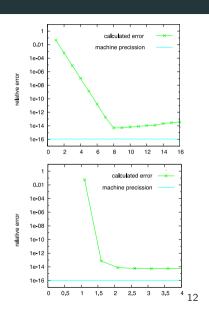
Approximation Error

One can derive approximation error estimations for the NFFT. For specific φ (i.e. Kaiser-Bessel functions) one can show that the approximation error can be adjusted to be lower than tha floating point precission (64 bit $\rightarrow \alpha = 2$ and m=6 for the Kaiser-Bessel window).

Since α and m are independent of N and M we end up

with an algorithmic complexity of

$$\mathcal{O}(N \log N + M) \ll \mathcal{O}(NM)$$



Matrix-Vector Notation

The NFFT can also been expressed in matrix vector notation. Let

$$\hat{oldsymbol{f}}:=(\hat{f}_k)_{k=-rac{N}{2}}^{rac{N}{2}-1}\in\mathbb{C}^N,\quad oldsymbol{f}:=(f_j)_{j=0}^{M-1}\in\mathbb{C}^M$$

and

$$\mathbf{A} := \left(e^{-2\pi i k x_j} \right)_{j=0,\dots,M-1; k=-\frac{N}{2},\dots,\frac{N}{2}-1} \in \mathbb{C}^{M \times N}.$$

then

$$m{f} = m{A}m{\hat{f}} pprox m{B}$$
 $m{\mathcal{F}}$ $m{\mathcal{D}}$ $m{\hat{f}}$

Here we note that \boldsymbol{B} is a sparse matrix (i.e. has only few non-zero entries).

Implementation

The window function φ and $c_k(\tilde{\varphi})$ are usually expensive to calculate and should therefore be cached. There are two possibilities for φ

- 1. Create a lookup table for φ
- 2. Store ${\it B}$ in a sparse matrix format (CRS / CCS)

Adjoint NFFT

In addition to the regular NFFT one often also needs the adjoint NFFT. It maps from non-equidistant samples to equidistant samples, wheras the NFFT is the other way around.

$$\hat{f}_{k} = \sum_{j=0}^{M-1} f_{j} e^{2\pi i k x_{j}} \quad k = -\frac{N}{2}, \dots, \frac{N}{2} - 1$$

$$\approx \frac{1}{\alpha N c_{k}(\tilde{\varphi})} \sum_{l=-\frac{\alpha N}{2}}^{\frac{\alpha N}{2} - 1} \underbrace{\left(\sum_{j=0}^{M-1} f_{j} \tilde{\psi}\left(x_{j} - \frac{l}{\alpha N}\right)\right)}_{\text{discrete convolution}} e^{2\pi i k \frac{l}{\alpha N}}$$

$$\underbrace{\sum_{l=-\frac{\alpha N}{2}}^{M-1} \left(\sum_{j=0}^{M-1} f_{j} \tilde{\psi}\left(x_{j} - \frac{l}{\alpha N}\right)\right)}_{\text{discrete convolution}} e^{2\pi i k \frac{l}{\alpha N}}$$
appodization

Adjoint NFFT

In matrix vector notation:

$$\boldsymbol{\hat{f}} = \boldsymbol{A}^{\mathsf{H}} \boldsymbol{f} \approx \boldsymbol{D}^{\mathsf{H}} \boldsymbol{F}^{\mathsf{H}} \boldsymbol{B}^{\mathsf{H}} \boldsymbol{f}$$

Window Function (Kaiser-Bessel)

There are various suitable window functions for which error estimations have been derived. The best is the Kaiser-Bessel window, which is defined as

$$\varphi(v) := \begin{cases} \frac{1}{2m} I_0 \left(bm \sqrt{1 - \left(\frac{\alpha N v}{m} \right)^2} \right) & \text{falls} \quad |v| \le \frac{m}{\alpha N} \quad (b := \pi (2 - \frac{1}{\alpha})), \\ 0 & \text{falls} \quad |v| > \frac{m}{\alpha N} \end{cases}$$

where $I_k : \mathbb{C} \to \mathbb{C}$, $k \in \mathbb{N}_0$ is the modified Bessel function of the first kind:

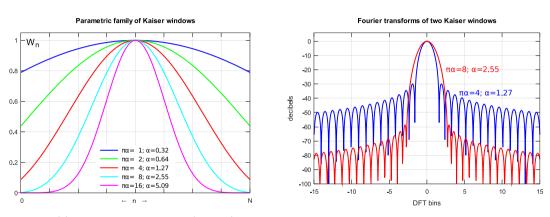
$$I_k(x) := \sum_{r=0}^{\infty} \frac{(\frac{x}{2})^{2r+k}}{(r+k)!r!}.$$

Window Function (Kaiser-Bessel)

The Fourier transform of the Kaiser-Bessel window can be shown to be

$$\hat{\varphi}(z) = \frac{1}{\alpha N} \operatorname{sinc} \left(\sqrt{\left(\frac{2\pi mz}{\alpha N}\right)^2 - b^2 m^2} \right)$$
$$= \frac{1}{\alpha N} \sum_{n=0}^{\infty} \frac{1}{(2n+1)!} \left(b^2 m^2 - \left(\frac{2\pi mz}{\alpha N}\right)^2 \right)^n.$$

Window Function (Kaiser-Bessel)



https://en.wikipedia.org/wiki/Kaiser_window

Multidimensional NFFT

The NDFT and the NFFT can be also formulated / derived for multidimensional signals:

NFFT

$$f_j := \sum_{\mathbf{k} \in I_N^d} \hat{f}_{\mathbf{k}} \mathrm{e}^{-2\pi \mathrm{i} \mathbf{k} \mathbf{x}_j}, \qquad j = 0, \dots M - 1$$

Adjoint NFFT

$$\hat{f}_{\mathbf{k}} = \sum_{j=0}^{M-1} f_j e^{2\pi i \mathbf{k} \mathbf{x}_j}, \qquad \mathbf{k} \in I_{\mathbf{N}}^d$$

where the index set I_{N}^{d} with $N = (N_0, \dots, N_{d-1})^T \in \mathbb{N}^d$ is defined as

$$I_{\mathbf{N}}^d := \left\{ -\frac{N_1}{2}, \dots, \frac{N_1}{2} - 1 \right\} \times \dots \times \left\{ -\frac{N_d}{2}, \dots, \frac{N_d}{2} - 1 \right\}$$

and d is the dimensionality of the tranform.

Inverse NFFT

In general the adoint NFFT is not (exactly) the inverse NFFT, i.e.

$$A^HA \neq I$$

However, one can derive an approximation to the (pseudo)inverse quite efficiently.

To this end we first consider the NDFT

$$f(x_j) = \sum_{k=-\frac{N}{2}}^{\frac{N}{2}-1} \hat{f}_k e^{-2\pi i k x_j}, \quad j = 0, \dots, M-1$$

We now extend the sum to $\pm \infty$, which leads to the Fourier series

$$f(x_j) = \sum_{k=-\infty}^{\infty} \hat{f}_k e^{-2\pi i k x_j}, \quad j = 0, \dots, M-1$$

where the coefficients \hat{f}_k have been zero-padded.

Inverse NFFT

The Fourier coefficients \hat{f}_k can be calculated by

$$\hat{f}_k = \int_{-\frac{1}{2}}^{\frac{1}{2}} f(x) e^{2\pi i k x_j} dx$$
 $k = -\frac{k}{2}, \dots, \frac{k}{2} - 1$

Since f is only known at the sampling nodes x_j , we can only consider these when approximating the integral by a sum. When applying a rectangular quadrature rule, one obtains

$$\hat{f}_k pprox \sum_{j=0}^{M-1} w_j f(x_j) e^{2\pi i k x_j}$$
 $k = -\frac{k}{2}, \dots, \frac{k}{2} - 1$

where w_j , $j=0,\ldots,M-1$ are the quadrature weights. This is the adjoint NFFT with a pre-weighting. In matrix-vector notation this implies $\mathbf{A}^H \mathbf{W} \approx \mathbf{A}^+$, i.e. $\mathbf{A}^H \mathbf{W} \mathbf{A} \approx \mathbf{I}$.

Summary

- The NDFT is a generalization of the DFT
- The NFFT is an efficient implementation of the NDFT, which exploits a numerical approximation of the complex exponential
- The approximation error is known and can be adjusted to reach machine precision.
- In practice the convolution usually takes most of the computation time. With optimized parameters ($\alpha=1.25,\ m=2$) it is possible to make the convolution as fast as the FFT.
- There are various implementations of the NFFT. One reference implementation is the C library NFFT 3 (https://github.com/NFFT/nfft). Also a Julia package exists: https://github.com/tknopp/NFFT.jl